## NOTE

# On a Discrete Kolmogorov Criterion 

M. Finzel

Mathematical Institute, University of Erlangen-Nuremberg, Bismarckstrasse 1 1/2, 91054 Erlangen, Germany
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In this note we consider best approximation in 1-norm from subspaces of real $n$-dimensional spaces. Some discrete Kolmogorov-type criteria characterizing elements of best approximation are verified. © 2002 Elsevier Science (USA)

## 1. INTRODUCTION

Consider $l_{1}(n)$, i.e., $\mathbb{R}^{n}$ endowed with the 1 -norm $\|\cdot\|_{1}$, and let $U$ be an $r$-dimensional linear subspace of $\mathbb{R}^{n}, 0<r<n$. Let us denote the metric projection

$$
\begin{aligned}
P_{U}: \mathbb{R}^{n} & \rightarrow 2^{U}, \\
& x \mapsto\left\{u \in U:\|x-u\|_{1}=\operatorname{dist}(x ; U)\right\},
\end{aligned}
$$

where $\operatorname{dist}(x ; U)=\min _{u \in U}\|x-u\|_{1}$ is the distance of $x$ to the subspace $U$.
The famous Kolmogorov criterion characterizes all best approximants:
Classical Kolmogorov criterion. For $x \in \mathbb{R}^{n}, u^{*} \in U$, and $Z_{x-u^{*}}:=$ $\{1,2, \ldots, n\} \backslash \operatorname{supp}\left(x-u^{*}\right)$ we have

$$
\begin{equation*}
u^{*} \in P_{U}(x) \Leftrightarrow \sum_{i \notin Z_{x-u^{*}}} \operatorname{sgn}\left(x_{i}-u^{*}\right) \cdot u_{i} \leqslant \sum_{i \in Z_{x-u^{*}}}\left|u_{i}\right| \quad \text { for all } \quad u \in U . \tag{1}
\end{equation*}
$$

Here supp $y$ denotes the support of the vector $y \in \mathbb{R}^{n}$, the set of not vanishing components of $y$.

It goes back to Gauß that for each $x$ a best approximant in $U$ exists which interpolates $x$ in at least $r$ components, i.e., for each $x \in \mathbb{R}^{n}$ there exists a $u^{*} \in P_{U}(x)$ and pairwise distinct indices $v_{1}, \ldots, v_{r} \in\{1,2, \ldots, n\}$ with

$$
x_{v_{p}}=u_{v_{p}}^{*}, \quad 1 \leqslant \rho \leqslant r .
$$

Most algorithms which determine a best approximant of $x$ in $U$ are based on this fact. For this particular purpose the Kolmogorov criterion has been specialized and discretized such that (1) needs to be checked for only finitely
many points $u$ in $U$, see Bloomfield and Steiger [1] or Pinkus [5] for details.
Pinkus [5, Prop. 7.6] also gives a proof of this fact by contradiction.
First we give a discretized formulation of the restricted Kolmogorov criterion. The criterion, however, characterizes only those best approximants of a given vector $x$ which interpolates $x$ in at least $r$ components:

Discrete restricted Kolmogorov criterion. For $x \in \mathbb{R}^{n}$ and $u^{*} \in U$ with $Z=Z_{x-u^{*}}:=\{1,2, \ldots, n\} \backslash \operatorname{supp}\left(x-u^{*}\right), \operatorname{card} Z \geqslant r$ and $\operatorname{rank}\left[\begin{array}{l}U \\ Z\end{array}\right]=r$, we have

$$
u^{*} \in P_{U}(x) \Leftrightarrow \sum_{i \notin Z_{x-u^{*}}} \operatorname{sgn}\left(x_{i}-u_{i}^{*}\right) \cdot u_{i} \leqslant \sum_{i \in Z_{x-u^{*}}}\left|u_{i}\right|
$$

for all elementary vectors $u \in U$ for which an index set $J \subset Z_{x-u^{*}}$ exists with

$$
\operatorname{card} J=r, \quad \operatorname{rank}\left[\begin{array}{l}
U \\
J
\end{array}\right]=r, \quad \text { and } \quad \operatorname{card}(\operatorname{supp} u \cap J)=1 .
$$

Let $U^{\perp}$ denote the orthogonal complement of $U$, and

$$
\left[\begin{array}{l}
U \\
J
\end{array}\right]=\left[\begin{array}{c}
U \\
v_{1} \cdots v_{s}
\end{array}\right]=\left[\begin{array}{ccc}
v_{v_{1}}^{(1)} & \cdots & v_{v_{1}}^{(r)} \\
\vdots & & \vdots \\
v_{v_{s}}^{(1)} & \cdots & v_{v_{s}}^{(r)}
\end{array}\right],
$$

where $v^{(1)}, \ldots, v^{(r)}$ is an arbitrary basis of $U$ and $J=\left\{v_{1}, \ldots, v_{s}\right\}$.
Elementary vectors of a subspace are vectors with minimal support in the following sense: The vector $u \in U$ is elementary if and only if $w \in U$ with supp $w \subset \operatorname{supp} u$ implies $w=\lambda \cdot u$ for some $\lambda \in \mathbb{R}$, see Rockafellar [6, 203ff].

In general, however, there exist best approximants which interpolate the given vector $x$ in less than $r$ components. For these approximants the discrete restricted Kolmogorov criterion above is not applicable. Nevertheless, in this general situation the Kolmogorov criterion also allows a discrete formulation which unifies both advantages of the classical and the discrete restricted criterion. In characterizes best approximants, in general, and requires only to check (1) for elementary vectors of $U$ :

Theorem (Discrete Kolmogorov criterion). For $x \in \mathbb{R}^{n}, u^{*} \in U$, and $Z_{x-u^{*}}:=\{1,2, \ldots, n\} \backslash \operatorname{supp}\left(x-u^{*}\right)$ we have

$$
u^{*} \in P_{U}(x) \Leftrightarrow \sum_{i \notin Z_{x-u^{*}}} \operatorname{sgn}\left(x_{i}-u_{i}^{*}\right) \cdot u_{i} \leqslant \sum_{i \in Z_{x-u^{*}}}\left|u_{i}\right|
$$

for all elementary vectors $u$ in $U$.
Note, if an elementary vector $u \in U$ satisfies the inequality above, so does the elementary vector $\lambda u, \lambda>0$. In other words, it is sufficient to check the inequality above for all (finitely many) extremal points of the polyhedron $Q$, see Lemma 1(ii), below.

## 2. PROOF FOR THE DISCRETE KOLMOGOROV CRITERIA

In this section we first formulate a lemma which characterizes elementary vectors from different points of view. Then we prove the theorem. Its proof needs a technical lemma on elementary vectors. Finally, we give a direct proof of Theorem 1.

The following lemma states equivalent characterizations of elementary vectors:

Lemma 1. For a vector $u$ in $U$ the following statements are equivalent:
(i) $u \in U$ is an elementary vector;
(ii) $u /\|u\|_{1} \in \operatorname{ext} Q$, where $Q=U \cap \overline{b_{1}^{1}(0)}$ denotes the intersection of $U$ with the closed unit ball in $l_{1}(n) ; Q$ is an $r$-dimensional closed convex and symmetric polyhedron;
(iii) $\operatorname{rank}\left[\begin{array}{c}U^{\perp} \\ \operatorname{supp} u\end{array}\right]=\operatorname{rank}\left[\begin{array}{c}U^{\perp} \\ \mu_{1} \cdots \mu_{m-1}\end{array}\right]=\operatorname{card} \operatorname{supp} u-1$
for all $\left\{\mu_{1}, \ldots, \mu_{m-1}\right\} \subset \operatorname{supp} u$ and $\operatorname{card} \operatorname{supp} u=m$;

$$
\text { (iv) } \quad \operatorname{rank}\left[\begin{array}{c}
U \\
\operatorname{supp}^{\mathrm{c}} u
\end{array}\right]=r-1 \quad \text { and } \quad \operatorname{rank}\left[\begin{array}{c}
U \\
\operatorname{supp}^{\mathrm{c}} u \cup\{\mu\}
\end{array}\right]=r
$$

for all $\mu \in \operatorname{supp} u$.
Here supp ${ }^{\text {c }} u:=\{1,2, \ldots, n\} \backslash$ supp $u$ denotes the complementary index set of the support set of $u$.

For the equivalence of (i), (ii), and (iii) see [2], while the equivalence of (iii) and (iv) follows from the following relation, see [3]:
$\operatorname{rank}\left[\begin{array}{c}U \\ \{1,2, \ldots, n\} \backslash I\end{array}\right]=\operatorname{rank}\left[\begin{array}{c}U^{\perp} \\ I\end{array}\right]+r-\operatorname{card} I \quad$ for any $\quad I \subset\{1,2, \ldots, n\}$.
Rockafellar [6] defined elementary vectors in terms of their supports. The support of an elementary vector uniquely determines it up to a scalar factor. The geometric characterization (ii) of Lemma 1 eliminates this degree of freedom by normalizing the elementary vector $u \in U:\|u\|_{1}=1$. All normalized elementary vectors lie on the $l_{1}(n)$-unit sphere and form exactly the set of vertices of the polyhedron $Q=U \cap \overline{b_{1}^{1}(0)}$. Clearly, there are only finitely many extremal points of $Q$ and in this sense there are only
finitely many elementary vectors in the subspace, which are also called elementary directions. The collection of all elementary directions of a linear subspace spans the subspace; in general, however, the elementary directions are linearly dependent. Moreover, each elementary vector $u$ of the subspace $U$ has at least $r-1$ zero components, and, consequently, at most $n-r+1$ components which do not vanish.

From Lemma 1(iv) it follows that each elementary vector $u$ in $U$ has a representation $u=\sum_{\rho=1}^{r} \alpha_{\rho} v^{(\rho)}$, where $\alpha_{1}, \ldots, \alpha_{r}$ is a non-vanishing solution of the homogeneous system of linear equalities $\sum_{\rho=1}^{r} \alpha_{\rho} v_{v}^{(\rho)}=0, v \in \operatorname{supp}^{\mathrm{c}} u$.

On the other hand, it follows from Lemma 1(iii) that each elementary vector $u$ in $U$ is a normal vector of the hyperplane in $\mathbb{R}^{\text {card supp } u}$ spanned by the columns of the matrix $\left[\begin{array}{c}U^{\perp} \\ \operatorname{supp} u\end{array}\right]$ which has rank deficiency one. Assume card supp $u=m$ and $\operatorname{rank}\left[\begin{array}{c}w^{(1)} \ldots w^{(m-1)} \\ \operatorname{supp} u\end{array}\right]=m-1$ where $w^{(1)}, \ldots, w^{(m-1)} \in U^{\perp}$, then the elementary vector $u$ is given by the generalized vector (or cross) product of the column vectors of the $m \times(m-1)$-matrix above. For more information on elementary vectors see [2] and [4].

Lemma 2. For each vector $u$ in $U$ there exist elementary vectors $u^{(1)}, \ldots$, $u^{(l)} \in U$ and scalars $\alpha_{1}, \ldots, \alpha_{l} \geqslant 0$ with

$$
u=\sum_{\lambda=1}^{l} \alpha_{\lambda} u^{(\lambda)} \quad \text { and } \quad u_{i}^{(\lambda)} \cdot u_{i} \geqslant 0, \quad 1 \leqslant i \leqslant n, \quad 1 \leqslant \lambda \leqslant l .
$$

Proof. Assume without loss of generality $\|u\|_{1}=1$. Then $u$ belongs to a face of the relative boundary of the polyhedron $Q$. Let $u^{(1)}, \ldots, u^{(l)}$ be the extremal points of this face. Consequently $u^{(1)}, \ldots, u^{(l)}$ are also extremal points of $Q$, and hence elementary vectors in $U$.

Remember that each hyper-face of the unit ball $\overline{b_{1}^{1}(0)}$ belongs to a closed orthant of $\mathbb{R}^{n}$, and so does each face of $Q$. We have $u_{i}^{(\lambda)} \cdot u_{i} \geqslant 0$ for all $1 \leqslant i \leqslant n$ and all $1 \leqslant \lambda \leqslant l$. Finally, $u$ is a convex combination of the extremal points of the face of $Q$ where $u$ belongs to; i.e., there exist $\alpha_{1}, \ldots, \alpha_{l}$ $\geqslant 0$ with $u=\sum_{\lambda=1}^{l} \alpha_{\lambda} u^{(\lambda)}$.

Proof of the discrete Kolmogorov criterion. " $\Rightarrow$ ": It follows from the classical Kolmogorov criterion.
" $\Leftarrow "$ : Let $u^{*}$ be in $\mathbb{R}^{n}$, and $u \in U$. By Lemma 2 there exist elementary vectors $u^{(1)}, \ldots, u^{(l)}$ in $U$ and scalars $\alpha_{1}, \ldots, \alpha_{l} \geqslant 0$ with $u=\sum_{\lambda=1}^{l} \alpha_{\lambda} u^{(\lambda)}$ and $u_{i}^{(\lambda)} \cdot u_{i} \geqslant 0,1 \leqslant i \leqslant n, 1 \leqslant \lambda \leqslant l$. By assumption we have for $1 \leqslant \lambda \leqslant l$

$$
\sum_{i \notin Z_{x-u^{*}}} \operatorname{sgn}\left(x_{i}-u_{i}^{*}\right) \cdot u_{i}^{(\lambda)} \leqslant \sum_{i \in Z_{x-u^{*}}}\left|u_{i}^{(\lambda)}\right|,
$$

and hence

$$
\begin{aligned}
\sum_{i \notin Z_{x-u^{*}}} \operatorname{sgn}\left(x_{i}-u_{i}^{*}\right) \cdot \sum_{\lambda=1}^{l} \alpha_{\lambda} u_{i}^{(\lambda)} & \leqslant \sum_{i \in Z_{x-u^{*}}} \sum_{\lambda=1}^{l} \alpha_{\lambda}\left|u_{i}^{(\lambda)}\right| \\
& =\sum_{i \in Z_{x-u^{*}}}\left|\sum_{\lambda=1}^{l} \alpha_{\lambda} u_{i}^{(\lambda)}\right|
\end{aligned}
$$

The last equality holds because of all summands have the same sign or vanish. So the classical Kolmogorov criterion is satisfied and hence $u^{*}$ is in $P_{U}(x)$.

A direct proof of the discrete restricted Kolmogorov criterion is based on the argument given above and the following lemma. For this we need some notation. Let be $x \in \mathbb{R}^{n}, u^{*} \in P_{U}(x)$, and $Z:=\{1,2, \ldots, n\} \backslash \operatorname{supp}\left(x-u^{*}\right)$ with card $Z=s \geqslant r$ and $\operatorname{rank}\left[\begin{array}{c}U \\ Z\end{array}\right]=r$. The orthogonal projection $\Pi_{Z}: \mathbb{R}^{n} \rightarrow$ $\mathbb{R}^{s}, y \mapsto \bar{y}$ with $\bar{y}_{i}=y_{i}$ for $i \in Z$ maps the $r$-dimensional linear subspace $U$ to the $r$-dimensional linear subspace $\bar{U}$ of $\mathbb{R}^{s}$, and the basis vectors $v^{(1)}, \ldots$, $v^{(r)}$ of $U$ to the basis vectors $\bar{v}^{(\rho)}=\Pi_{Z}\left(v^{(\rho)}\right)$ of $\bar{U}, 1 \leqslant \rho \leqslant r$.

Lemma 3. Under the notation given above, $\bar{u}$ is an elementary vector in $\bar{U}$ if and only if $\bar{u}=\Pi_{Z}(u)$ for an elementary vector $u$ in $U$ with

$$
1 \leqslant \operatorname{card}(\operatorname{supp} u \cap Z) \quad \text { and } \quad \operatorname{rank}\left[\begin{array}{c}
U \\
\operatorname{supp}^{c} u \cap Z
\end{array}\right] \geqslant r-1 .
$$

Proof. " $\Rightarrow$ ": For $\bar{u} \in \bar{U}$ we have a unique representation $\bar{u}=\sum_{\rho=1}^{r} \beta_{\rho} \bar{v}^{(\rho)}$, and hence $u=\sum_{\rho=1}^{r} \beta_{\rho} v^{(\rho)}$ and $\Pi_{z}(u)=\bar{u}$. Let $w$ be in $U$ with supp $w \subset$ $\operatorname{supp} u$. We have $\operatorname{supp} \Pi_{z}(w) \subset \operatorname{supp} \Pi_{z}(u)$, and hence $\Pi_{Z}(w)=\lambda \cdot \Pi_{Z}(u)$ for a $\lambda \in \mathbb{R}$. By uniqueness of the representation in terms of a basis of $\bar{U}$ and $U$, respectively, it follows that $w=\lambda \cdot u$; thus $u$ is elementary in $U$.

Since $\bar{u} \neq 0$ we have $1 \leqslant \operatorname{card} \operatorname{supp} \bar{u}=\operatorname{card}(\operatorname{supp} u \cap Z)$.
Moreover, since $\bar{u}$ is elementary, the system of linear equalities $\sum_{\rho=1}^{r} \gamma_{\rho} v_{i}^{(\rho)}=0, i \in\{1, \ldots, s\} \backslash \operatorname{supp} \bar{u}=\operatorname{supp}^{\mathrm{c}} u \cap Z$ has a one-dimensional set of solutions, and consequently, $\operatorname{rank}\left[\operatorname{supp}^{{ }^{U} u \cap z}\right]=r-1$.
" $\Leftarrow "$ : The rank condition implies that there exists up to scalar multiplication only one vector $\bar{v}$ in $\bar{U}$ with $\operatorname{supp} \bar{v} \subset \operatorname{supp}^{\mathfrak{c}} u \cap Z=\operatorname{supp} \bar{z}$. From $0 \neq \bar{u}=\Pi_{Z}(u)$ we conclude $\bar{v}=\lambda \cdot \bar{u}$ for some $\lambda \in \mathbb{R}$, and hence $\bar{u}$ is elementary in $\bar{U}$.

Proof the discrete restricted Kolmogorov criterion. We only need to prove " $\Leftarrow$ ": Let $x$ be in $\mathbb{R}^{n}$ and $u^{*}$ in $U$.

Consider $u$ in $U$ and $\tilde{u}:=\Pi_{Z}(u)$. By Lemma 2 there exist elementary vectors $\bar{u}^{(1)}, \ldots, \bar{u}^{(l)}$ in $\bar{U}=\Pi_{Z}(U)$ and scalars $\alpha_{1}, \ldots, \alpha_{l} \geqslant 0$ with

$$
\tilde{u}=\sum_{\lambda=1}^{l} \alpha_{\lambda} \bar{u}^{(\lambda)} \quad \text { and } \quad \bar{u}_{i}^{(\lambda)} \cdot \tilde{u}_{i} \geqslant 0, \quad i \in Z, \quad 1 \leqslant \lambda \leqslant l .
$$

Let us consider $\bar{u}^{(\lambda)}$ more closely, $1 \leqslant \lambda \leqslant l$ : Since $\bar{u}^{(\lambda)}$ is elementary in $\bar{U}$, by Lemma 1 (iv) there exist indices $v_{1}, \ldots, v_{r-1} \in \operatorname{supp}^{\mathrm{c}} \bar{u}^{(\lambda)}$ such that

$$
\operatorname{rank}\left[\begin{array}{c}
U \\
\operatorname{supp}^{\mathrm{c}} \bar{u}^{(\lambda)} \cup\left\{v_{r}\right\}
\end{array}\right]=\operatorname{rank}\left[\begin{array}{l}
U \\
J
\end{array}\right]=r
$$

with $J=\left\{v_{1}, \ldots, v_{r}\right\}$. In particular, we have card $J=r$ and $\operatorname{card}\left(\operatorname{supp} \bar{u}^{(\lambda)} \cap J\right)$ $=1$. By Lemma 3 there exists an elementary vector $u^{(\lambda)}$ in $U$ with $\bar{u}^{(\lambda)}=$ $\Pi_{Z}\left(u^{(\lambda)}\right)$. Clearly, for $u^{(\lambda)}$ the index set $J \subset Z$ satisfies card $J=r, \operatorname{rank}\left[\begin{array}{l}U \\ J\end{array}\right]=r$ and $\operatorname{card}\left(\operatorname{supp} u^{(\lambda)} \cap J\right)=1$. Consequently,

$$
\sum_{i \notin Z} \operatorname{sgn}\left(x_{i}-u_{i}^{*}\right) \cdot u_{i}^{(\lambda)} \leqslant \sum_{i \in Z}\left|u_{i}^{(\lambda)}\right|, \quad 1 \leqslant \lambda \leqslant l,
$$

and hence

$$
\sum_{i \notin Z} \operatorname{sgn}\left(x_{i}-u_{i}^{*}\right) \cdot \sum_{\lambda=1}^{l} \alpha_{\lambda} u_{i}^{(\lambda)} \leqslant \sum_{i \in Z} \sum_{\lambda=1}^{l} \alpha_{\lambda}\left|u_{i}^{(\lambda)}\right|=\sum_{i \in Z}\left|\sum_{\lambda=1}^{l} \alpha_{\lambda} u_{i}^{(\lambda)}\right| .
$$

The last equality holds because all summands have the same sign or vanish. By $\operatorname{rank}\left[\begin{array}{c}U \\ J\end{array}\right]=r$ and $J \subset Z$ the elementary vectors $u^{(1)}, \ldots, u^{(l)}$ in $U$ are uniquely determined, and hence $u=\sum_{\lambda=1}^{l} \alpha_{\lambda} u^{(\lambda)}$. The classical Kolmogorov criterion is satisfied and consequently, $u^{*}$ in $P_{U}(x)$.

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